

Student ID _____

**Department of Mechanical Engineering
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Ph.D. Qualifying Exam in Fluid Mechanics

- Closed book, but one sheet (8.5" x 11", front and back) of your own notes with equations permitted.
- Some basic equations are provided on an attached information sheet.
- Answer all questions.
- All questions have the same weighting.

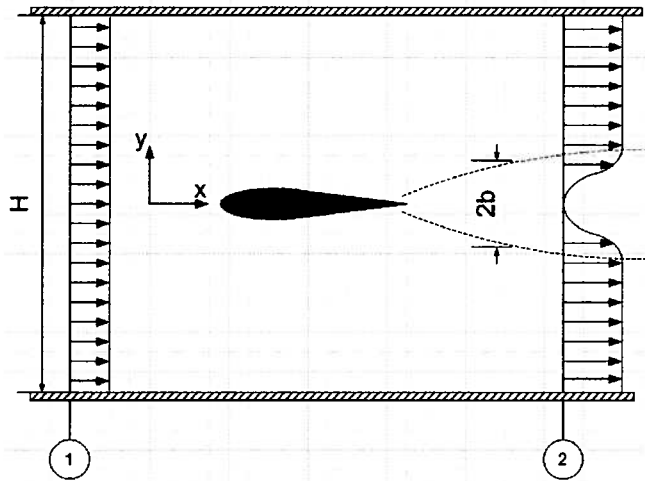
Exam prepared by

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Problem 1:

The drag force on an airfoil is being determined experimentally by mounting the airfoil in a wind-tunnel test section of height H , as shown in the figure. Velocity measurements upstream and downstream of the model, at stations labeled 1 and 2, respectively, are as shown. At station 1, the approaching flow is potential with a uniform velocity of 10 m/s (the boundary layers on the top and bottom walls may be neglected). At station 2, the velocity variation within the wake of the airfoil is given by $U_o/2[1 - \cos(\pi y/b)]$; where b is the wake half width and U_o is the freestream velocity. Assuming the flow of air (density = 1.2 kg/m^3) to be two dimensional, $b = 25 \text{ mm}$ at station 2, and $H = 250 \text{ mm}$, do the following:



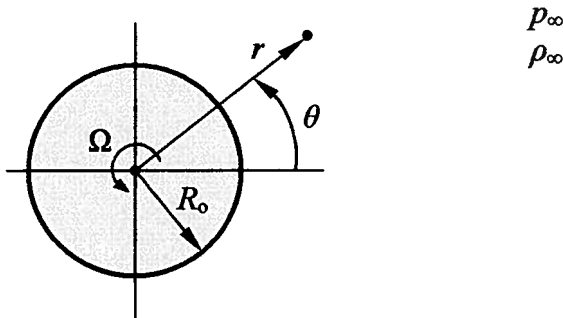
- Determine U_o at station 2
- Find the pressure difference ($p_1 - p_2$)
- Determine the drag force acting on the airfoil

Problem 2:

A bio-mechanical engineer wants to study the fluid dynamics associated with swimming of small fish *near the free surface of* ponds. To undertake a systematic study of this problem, the engineer proposes to build a robotic fish of a scale that is 10 times larger than the typical fish size of interest. Of primary interest is the ability of the robot (or model) to replicate the oscillatory movement of the fish tail. If the typical size of the real fish is about 1 cm long and it swims with a speed of 1 cm/s while moving its tail at a frequency of 10 Hz, what should be the test flow speed? What should be the frequency of tail movement in the test? You may assume the test is to be done using a mixture of water and glycerin as the test fluid (kinematic viscosity information for mixtures of water and glycerin with various proportions is given in an attached table. Also, for reference, common non-dimensional parameters in fluid mechanics are included as an attachment as well.

Problem 3:

A 2-D circular cylinder of radius R_0 is rotating with a constant angular velocity Ω about its axis (z-axis, out of the page). The surrounding fluid is air. Far away from the cylinder, air is at rest with its pressure and density given by p_∞ and ρ_∞ . Consider the flow generated long after the start of the cylinder rotation so that a steady state condition has been achieved with a temperature uniform at room temperature T . The resulting flow field can be considered incompressible, even though the air density is not a constant. The effects of gravity can be neglected. The flow field can be assumed to be axisymmetric and two-dimensional with the velocity field being purely azimuthal (i.e. along θ direction)



- (A) Determine the velocity, density and pressure distributions $u_\theta(r)$, $\rho(r)$, $p(r)$ in terms of the known parameters of the flow. Assume air behaves as a perfect gas, for which the sound speed a is given by $a^2 = \gamma RT$, where γ is the specific heat ratio, R the gas constant, and T the absolute temperature.
- (B) Derive the expression for the ratio of air density ρ_0 at the cylinder surface to that far away from the cylinder (i.e. ρ_0 / ρ_∞) in terms of the problem parameters (R_0 , Ω , a , γ). Calculate ρ_0 / ρ_∞ for a cylinder of radius $R_0 = 1$ m rotating at a speed $\Omega = 1500$ rpm. Recall that for air $\gamma = 1.4$ and at room temperature the sound speed is $a = 330$ m/s.

Problem 4:

A baseball 2.95 inches (0.075 m) in diameter with a mass of 0.01 slug (0.154 kg) leaves the pitcher's hand with a velocity of 90 mph (145 km/h). Estimate the velocity of the ball it reaches the catcher 60.5 ft (18.44 m) away. For the purpose of this estimate, assume the ball does not spin and travels straight.

Integral mass conservation equation:

$$0 = \frac{\partial}{\partial t} \int_{CV} \rho dV + \int_{CS} \rho \vec{V} \cdot d\vec{A}$$

Integral momentum equation:

$$\vec{F} = \vec{F}_s + \vec{F}_B = \frac{\partial}{\partial t} \int_{CV} \vec{V} \rho dV + \int_{CS} \vec{V} \rho \vec{V} \cdot d\vec{A}$$

The Equation of Continuity

Rectangular Coordinates (x, y, z):

$$\frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x}(\rho v_x) + \frac{\partial}{\partial y}(\rho v_y) + \frac{\partial}{\partial z}(\rho v_z) = 0$$

Cylindrical Coordinates (r, θ, z):

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r}(\rho r v_r) + \frac{1}{r} \frac{\partial}{\partial \theta}(\rho v_\theta) + \frac{\partial}{\partial z}(\rho v_z) = 0$$

Momentum Equations for Incompressible Newtonian Fluid with Constant Viscosity (μ)

Rectangular Coordinates (x, y, z):

$$\rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) = \mu \left[\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right] - \frac{\partial p}{\partial x} + \rho g_x$$

$$\rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) = \mu \left[\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right] - \frac{\partial p}{\partial y} + \rho g_y$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) = \mu \left[\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right] - \frac{\partial p}{\partial z} + \rho g_z$$

Cylindrical Coordinates (r, θ, z):

$$\rho \left(\frac{\partial v_r}{\partial t} + v_r \frac{\partial v_r}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_r}{\partial \theta} - \frac{v_\theta^2}{r} + v_z \frac{\partial v_r}{\partial z} \right) = \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r v_r) \right) + \frac{1}{r^2} \frac{\partial^2 v_r}{\partial \theta^2} + \frac{\partial^2 v_r}{\partial z^2} - \frac{2}{r^2} \frac{\partial v_\theta}{\partial \theta} \right] - \frac{\partial p}{\partial r} + \rho g_r$$

$$\rho \left(\frac{\partial v_\theta}{\partial t} + v_r \frac{\partial v_\theta}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r v_\theta}{r} + v_z \frac{\partial v_\theta}{\partial z} \right) = \mu \left[\frac{\partial}{\partial r} \left(\frac{1}{r} \frac{\partial}{\partial r} (r v_\theta) \right) + \frac{1}{r^2} \frac{\partial^2 v_\theta}{\partial \theta^2} + \frac{\partial^2 v_\theta}{\partial z^2} + \frac{2}{r^2} \frac{\partial v_r}{\partial \theta} \right] - \frac{1}{r} \frac{\partial p}{\partial \theta} + \rho g_\theta$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_r \frac{\partial v_z}{\partial r} + \frac{v_\theta}{r} \frac{\partial v_z}{\partial \theta} + v_z \frac{\partial v_z}{\partial z} \right) = \mu \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 v_z}{\partial \theta^2} + \frac{\partial^2 v_z}{\partial z^2} \right] - \frac{\partial p}{\partial z} + \rho g_z$$

Table C-3 Components of the Stress Tensor for Newtonian Fluids

Rectangular Coordinates (x, y, z)	Cylindrical Coordinates (r, θ, z)
$\tau_{xx} = \mu \left[2 \frac{\partial v_x}{\partial x} - \frac{2}{3} (\nabla \cdot \mathbf{v}) \right]$	$\tau_{rr} = \mu \left[2 \frac{\partial v_r}{\partial r} - \frac{2}{3} (\nabla \cdot \mathbf{v}) \right]$
$\tau_{yy} = \mu \left[2 \frac{\partial v_y}{\partial y} - \frac{2}{3} (\nabla \cdot \mathbf{v}) \right]$	$\tau_{\theta\theta} = \mu \left[2 \left(\frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{v_r}{r} \right) - \frac{2}{3} (\nabla \cdot \mathbf{v}) \right]$
$\tau_{zz} = \mu \left[2 \frac{\partial v_z}{\partial z} - \frac{2}{3} (\nabla \cdot \mathbf{v}) \right]$	$\tau_{zz} = \mu \left[2 \frac{\partial v_z}{\partial z} - \frac{2}{3} (\nabla \cdot \mathbf{v}) \right]$
$\tau_{xy} = \tau_{yx} = \mu \left[\frac{\partial v_x}{\partial y} + \frac{\partial v_y}{\partial x} \right]$	$\tau_{r\theta} = \tau_{\theta r} = \mu \left[r \frac{\partial}{\partial r} \left(\frac{v_\theta}{r} \right) + \frac{1}{r} \frac{\partial v_r}{\partial \theta} \right]$
$\tau_{yz} = \tau_{zy} = \mu \left[\frac{\partial v_y}{\partial z} + \frac{\partial v_z}{\partial y} \right]$	$\tau_{\theta z} = \tau_{z\theta} = \mu \left[\frac{\partial v_\theta}{\partial z} + \frac{1}{r} \frac{\partial v_z}{\partial \theta} \right]$
$\tau_{zx} = \tau_{xz} = \mu \left[\frac{\partial v_z}{\partial x} + \frac{\partial v_x}{\partial z} \right]$	$\tau_{zr} = \tau_{rz} = \mu \left[\frac{\partial v_z}{\partial r} + \frac{\partial v_r}{\partial z} \right]$
$(\nabla \cdot \mathbf{v}) = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$	$(\nabla \cdot \mathbf{v}) = \frac{1}{r} \frac{\partial}{\partial r} (rv_r) + \frac{1}{r} \frac{\partial v_\theta}{\partial \theta} + \frac{\partial v_z}{\partial z}$

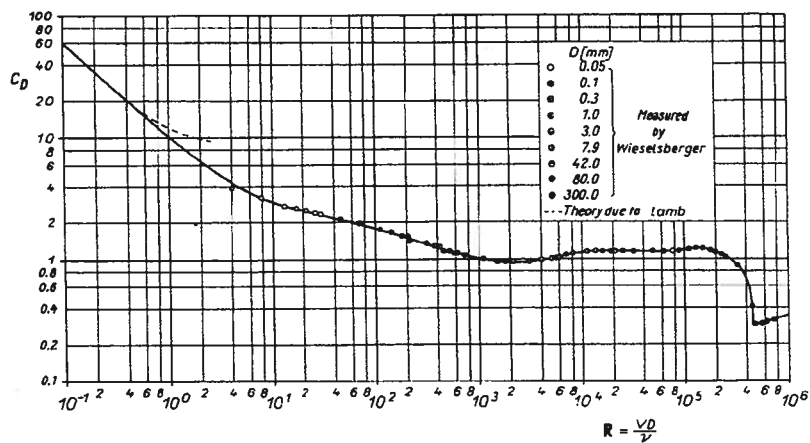


Fig. 1.4. Drag coefficient for circular cylinders as a function of the Reynolds number

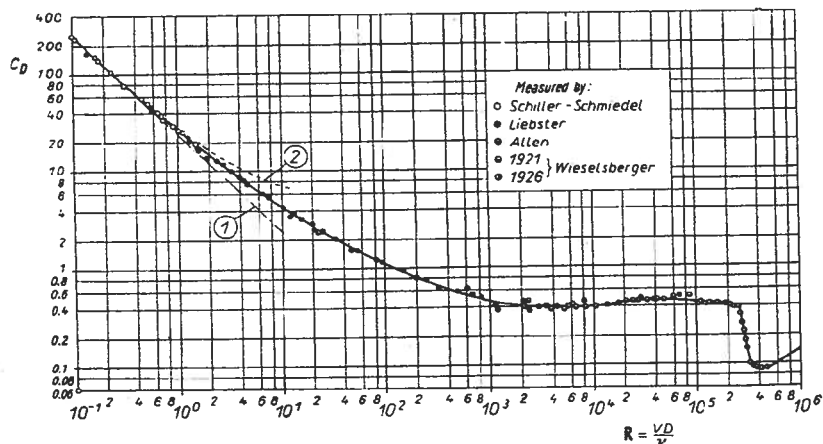


Fig. 1.5. Drag coefficient for spheres as a function of the Reynolds number
Curve (1): Stokes' theory, eqn. (6.10); curve (2): Oseen's theory, eqn. (6.18)

Curve (1), Stokes' theory:
 $C_D = 24/R$

Table 5.2 Dimensionless Groups in Fluid Mechanics

Parameter	Definition	Qualitative ratio of effects	Importance
Reynolds number	$Re = \frac{\rho UL}{\mu}$	$\frac{\text{Inertia}}{\text{Viscosity}}$	Always
Mach number	$Ma = \frac{U}{a}$	$\frac{\text{Flow speed}}{\text{Sound speed}}$	Compressible flow
Froude number	$Fr = \frac{U^2}{gL}$	$\frac{\text{Inertia}}{\text{Gravity}}$	Free-surface flow
Weber number	$We = \frac{\rho U^2 L}{Y}$	$\frac{\text{Inertia}}{\text{Surface tension}}$	Free-surface flow
Rossby number	$Ro = \frac{U}{\Omega_{\text{earth}} L}$	$\frac{\text{Flow velocity}}{\text{Coriolis effect}}$	Geophysical flows
Cavitation number (Euler number)	$Ca = \frac{p - p_v}{\rho U^2}$	$\frac{\text{Pressure}}{\text{Inertia}}$	Cavitation
Prandtl number	$Pr = \frac{\mu c_p}{k}$	$\frac{\text{Dissipation}}{\text{Conduction}}$	Heat convection
Eckert number	$Ec = \frac{U^2}{c_p T_0}$	$\frac{\text{Kinetic energy}}{\text{Enthalpy}}$	Dissipation
Specific-heat ratio	$k = \frac{c_p}{c_v}$	$\frac{\text{Enthalpy}}{\text{Internal energy}}$	Compressible flow
Strouhal number	$St = \frac{\omega L}{U}$	$\frac{\text{Oscillation}}{\text{Mean speed}}$	Oscillating flow
Roughness ratio	$\frac{\epsilon}{L}$	$\frac{\text{Wall roughness}}{\text{Body length}}$	Turbulent, rough walls
Grashof number	$Gr = \frac{\beta \Delta T g L^3 \rho^2}{\mu^2}$	$\frac{\text{Buoyancy}}{\text{Viscosity}}$	Natural convection
Rayleigh number	$Ra = \frac{\beta \Delta T g L^3 \rho c_p}{\mu k}$	$\frac{\text{Buoyancy}}{\text{Viscosity}}$	Natural convection
Temperature ratio	$\frac{T_w}{T_0}$	$\frac{\text{Wall temperature}}{\text{Stream temperature}}$	Heat transfer
Pressure coefficient	$C_p = \frac{p - p_\infty}{\frac{1}{2} \rho U^2}$	$\frac{\text{Static pressure}}{\text{Dynamic force}}$	Aerodynamics, hydrodynamics
Lift coefficient	$C_L = \frac{L}{\frac{1}{2} \rho U^2 A}$	$\frac{\text{Lift force}}{\text{Dynamic force}}$	Aerodynamics, hydrodynamics
Drag coefficient	$C_D = \frac{D}{\frac{1}{2} \rho U^2 A}$	$\frac{\text{Drag force}}{\text{Dynamic force}}$	Aerodynamics, hydrodynamics
Friction factor	$f = \frac{h_f}{(V^2/2g)(L/d)}$	$\frac{\text{Friction head loss}}{\text{Velocity head}}$	Pipe flow
Skin friction coefficient	$c_f = \frac{\tau_{\text{wall}}}{\rho V^2/2}$	$\frac{\text{Wall shear stress}}{\text{Dynamic pressure}}$	Boundary layer flow

Kinematic Viscosity of Glycerin-Water Mixture. Mass % indicates percentage of the mixture mass that Glycerin makes up. For example, 0.5% corresponds to a mixture of 99.5% water and 0.5% Glycerin.

Mass %	Kinematic Viscosity m^2/s
0.5	1.01161E-06
1	1.02149E-06
2	1.04507E-06
3	1.06855E-06
4	1.09192E-06
5	1.11617E-06
6	1.14328E-06
7	1.17114E-06
8	1.19996E-06
9	1.23246E-06
10	1.26383E-06
12	1.33015E-06
14	1.40142E-06
16	1.47973E-06
18	1.56595E-06
20	1.66077E-06
24	1.8824E-06
28	2.1371E-06
32	2.44847E-06
36	2.83928E-06
40	3.32575E-06
44	4.00559E-06
48	4.83304E-06
52	5.89494E-06
56	7.3115E-06
60	9.26366E-06
64	1.17298E-05
68	1.57014E-05
72	2.32808E-05
76	3.38769E-05
80	4.95656E-05
84	6.91749E-05
88	0.000119924
92	0.000309954
96	0.000623967
100	